

# AP Physics Formula Sheet

## Data

### Scientific Method

Observation  
 Define the Problem  
 Test/Experiment  
 Hypothesis  
 Collect Data/Manipulate  
 Conclusion

### Uncertainty

\*units (metrics)  
 \* measuring  
 \* sig. figs  
 \* Data  
 Manipulation

### Accuracy vs. Precision

Accuracy – closeness of results to a standard

Precision – closeness of results to each other

\*use same piece of equipment to collect data\*

### Qualitative vs. Quantitative

Qualitative – more on precision than accuracy

Quantitative – numbers count and are important

### Sig. Figs

Addition and Subtraction:

\*least # places after decimal

Multiplication

\*places after decimal count as sig. figs

$$2.5 \text{ cm} = 1 \text{ in}$$

### Vectors

Vectors (velocity) – has BOTH *magnitude* and *direction*

Scalars (speed) – has *magnitude* ONLY

\*time, mass, volume

### Metric System Abbr.

Mm - km - hm - dkm – m

dm - cm - mm - Mm(E-6) - nm(E-9)

### Mult. Component Vectors

1. 18m due S
2. 22m, 47deg. S of W
3. 10 m, 78deg. N of W
4. 30 m due E

\*(W&E) Sum of the

$$V_x = (0) + (-22 \cos 47) + (-10 \cos 78) + (30) = 12.9 \text{ m}$$

\*(N&S) Sum of the

$$V_y = (-18) + (-22 \sin 47) + (10 \sin 78) + (0) = -24.3 \text{ m}$$

\*Resultant  $u =$

$$((12.9)^2 + (24.3)^2)^{1/2} = 27.5 \text{ m}$$

$$* \theta = \tan^{-1}(24.3)$$

$$(12.9) = 62.0 \text{ deg}$$

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$$\underline{R = 28 \text{ m}, 62 \text{ deg S of E}}$$

## Kinematics

### Displacement

If + it's AWAY

If - it's TOWARD

### Velocity (m/s)

Use ONLY when *SPEED* is *CONSTANT*

1. does not include acceleration
2. does not include starting and stopping in the same place

$$v = \frac{\chi}{t}$$

### Acceleration (m/s/s)

\*speeding up or slowing down

$$a = \frac{v}{t}$$

## Kinematic Formulas

### X Direction

$$v = v_0 + at$$

$$\chi = \chi_0 + V_0 t + \frac{1}{2} at^2$$

$$\chi = \chi_0 + \frac{1}{2} (v + v_0)t$$

$$v^2 = v_0^2 + 2a(\chi - \chi_0)$$

### Y Direction

$$-gt$$

$$-\frac{1}{2}gt^2$$

.....

$$-2g \text{ (Change } \chi(0) = Y(0))$$

### Projectial Motion Half

\* Y determines time in air

\* compliment angles of 45deg have same range

<u>X</u>	<u>Y</u>
$\chi = V\chi t$	$Y = \frac{1}{2}gt^2$
$T = \chi$	
$V_{\chi}$	

### Full

\* 45deg has max. range

Steps:

1.  $v_0 \cos \theta_0 / v_0 \sin \theta_0$
2. Find the TIME (check Y)
3. Find the height / range

<u>X</u>	<u>Y</u>
$\chi = V\chi t$	$t = 2v_0/g$
$(V_X = v_0 \cos \theta_0)$	$(V_0 = v_0 \sin \theta_0)$

$$Y = \max = \frac{v_0^2}{2g}$$

### Force (N)

-Causes a change in motion (causes acceleration)

-Is a VECTOR quantity

**Equilibrium** – no acceleration, forces cancel, “at rest”

### Newton’s Laws of Motion

1. An object at rest will remain at rest until acted upon by an outside force  
INERTIA – directly related to mass
2. Acceleration is *directly* related to *Force* *indirectly* related to *mass*  
 $F = m a$  (1 kg m / s<sup>2</sup> = 1 Newton)
3. Action = equal and opposite reaction -can’t have only one force  
 $F a, b = - F b, a$

### Normal Force

- able to change until breaking point of whatever it’s holding
- acts perpendicularly to “holding” object
- comes from ground (except water)

## Newton's

1 N = 0.225 lbs      Mass is constant  
F = ma ----- F<sub>w</sub> = mg      N → kg (/ 9.8)  
Kg → N (x 9.8)

## Friction (F<sub>f</sub>)

1. two or more things must be touching
2. energy is transferred (heat, sound, etc) .
3. texture matters... NOT SURFACE AREA  
μ = coefficient of friction (Ratio of parallel force to perp. Force)

$$\mu = \frac{F_f}{F_N}$$

$$F_f = \mu mg \qquad F_f = F_w \text{ (on flat surface)}$$

$$\mu = \tan \theta \text{ (When } v \text{ is constant)}$$

Pressure: P = Force/area

4. opposes motion which causes deceleration
5. static – “starting F<sub>f</sub>” not moving (rolling) greater force than kinetic  
kinetic – moving (rolling, sliding, fluid)

## Equilibrium

Translational: the sum of forces equal zero

Rotational: the sum of torques equals zero

Complete: must have BOTH

Center of Gravity: center of distribution of mass

## Torque

Force with leverage causes rotation

Leverage: distance from fulcrum to for

\*Directly related to torque

$$\tau = F (\text{perp.}) l$$

## Circular Motion

Moving at a constant speed while accelerating

A = v → speed: constant

dxn: constantly changing

## Centripetal Acceleration

Inward seeking  $A_c = \frac{v^2}{r}$

### Centripetal Force

Causes centripetal acceleration

$$F_c = m a_c \quad (F = m a)$$

$$F_c = \frac{mv^2}{r} \text{ (N)}$$

You MUST have cent. F to keep something moving in a circle

**Centrifugal:** body's interpretation of cent. F

DOES NOT EXIST → feels inertia

Rotation: spinning on axis within object

Revolution: spinning on axis outside of object

### Linear / Angular

Linear : speed = distance / time → radius matters

$$57.3 \text{ deg} = 1 \text{ RADIAN}$$

$$1 \text{ rotation} = 2 \pi \text{ Radians} = 360 \text{ degrees}$$

**Angular:** speed = # rotations or revolutions / time

→ radius does NOT matter

\* by doubling the angular speed

you double the # of rotations

#### Linear

$$\chi \text{ (m)}$$

$$\chi = r \theta$$

$$v \text{ (m/s)}$$

$$v = r \omega$$

$$a \text{ (m/s/s)}$$

$$a = r \alpha$$

$$F \text{ (N)}$$

$$Ft = \tau$$

$$\text{Mass (m)}$$

$$F = m a$$

#### Angular

$$\theta \text{ (RAD)}$$

$$\omega \text{ (RAD / s)}$$

$$\alpha \text{ (RAD / s / s)}$$

$$\tau \text{ (Nm)}$$

$$I \text{ (mr)}$$

$$\tau = I \alpha$$

For linear

$$\omega = \omega_0 + at$$

See other corner  $\theta = \theta_0 + \omega_0 t + \frac{1}{2} at^2$

$$\theta = \theta_0 + \frac{1}{2}(\omega + \omega_0)t$$

$$\omega^2 = \omega_0^2 + 2a(\theta - \theta_0)$$

### Rotational Inertia

Resistance to begin or stop rotation

- Depends on amount of mass AND where it is placed  
Solid Sphere →  $\frac{2}{5} mr^2$     Solid Disk →  $\frac{1}{2} mr^2$   
Hollow Sphere →  $\frac{2}{3} mr^2$     Hollow Disk →  $1 mr^2$
- Velocity is indirectly related to Inertia
- Shape of object spinning makes the difference while spinning

### 3 Forces acting upon an object in circular motion

1. Centripetal Acceleration ( $a_c$ )
2. Angular Acceleration ( $\alpha$ )
3. Linear Acceleration ( $a$ )

### Conservation Laws

#### Momentum (N s)

Moving inertia (Newton's 2nd law)

*Momentum IS inertia...Inertia is NOT momentum*

Momentum is DIRECTLY related to mass and speed

$$p = mv \text{ (N s)}$$

Causes body to want to fly off tangent

#### Impulse

A change in momentum (how you feel p change)

$$\text{Force : } F = m a \rightarrow F = \frac{m\Delta v}{\Delta t}$$

Time : \* hidden variable\*

$$F\Delta t = m\Delta v = \Delta p$$

#### Conservation of Momentum

In the absence of an external force, the total momentum of a system is constant

$$m_1v_1 + m_2v_2 = m_1v_1 + m_2v_2$$

#### Work (J)

\*Need to apply force  $W = Fd$

\* implies motion

#### Power ( watt -- w )

$$P = \frac{w}{t} = \frac{fd}{t}$$

$$\frac{J}{s} = 1w = \frac{Nm}{s} = \frac{1kgm^2}{s^2}$$

$$1 \text{ horse power} = 746 \text{ w}$$

## Energy

Ability to do work

**Mechanical:** energy of motion or position

**Kinetic (K):** motion

$$K = \frac{1}{2}mv^2$$

Potential (U): position

$$U = mgh \text{ (J)} \quad (W = FD)$$

When not given distance...(or force)

When not given distance...(or force)

$$W = \frac{1}{2}mv^2 - \frac{1}{2}mv_0^2 \quad (W = \Delta K)$$

(K final) - (K initial)

## Conservation of Energy

Energy change from one to the other w/o any net loss

$$U_{\text{TOP}} = K_{\text{BOT}} \quad (mgh = \frac{1}{2}mv^2)$$

## Wave Motion

### Simple Harmonic Motion

A repeating motion in which the acceleration is directly related to the displacement (distance away from the equilibrium) and always directed towards equilibrium.

$$T = 2\pi \sqrt{\frac{l}{g}} \quad f = 1/T$$

## Cosine Curves

$$Y = A \cos B(x - C) + D$$

A = amplitude (0): how much energy it has

Cos B = period (  $2\pi / t$  ) : time, 1 oscillation

C = horz. Shift : human error

D = vert. Shift : distance, to x-axis

## Waves

\* Graphed SHM, transfer of energy

Vibration: WORK to get energy

Propagates : what energy moves through

Mechanical (light)                      Electromagnetic (sound)

Needs a medium                      does NOT need a medium

More dense – better                      less dense – better

## Mechanical Waves

**Transverse:** medium vibrates perp. to energy Most common ex. Guitar string, slinky

**Longitudinal:** medium vibrates para. to energy Has compressions ex: sound

Surface: both para. and perp. to energy “physics bob” ex: earthquakes, waves

## Principle of Superposition

Constructive Interference: added

Deconstructive: subtracting (adding negatives)

$$V = \frac{\lambda}{T} \quad V = \lambda f$$

## Standing Wave

A continuous wave train of equal amplitude (RAD), wavelength (m), and frequ. (Hz) (/sec) in the same medium creating nodes and antinodes.

**Boundary:** change in medium

(part of energy gets reflected, part gets absorbed)

**rigidity:** how much energy gets ABSORBED

close rigidity → more absorbed

different rigidity → more reflected

## Interference in Diffraction

Crest + crest = antinode Crest + trough = node

## Sound

A range of longitudinal wave frequ. to which the human ear is sensitive

Infra sonic

(Below 20 Hz.)

sonic spectrum

(20 Hz – 20,000 Hz)

ultra sonic

(20,000 Hz +)

1. **production** : needs vibration
2. **transition** : needs a medium → air
3. **reception** : must be heard

V sound = 340 m/s

V sound = 331 + . 6 (Temp.)

**Intensity:** measurable

How loud a sound is \* the time of flow of energy per unit area

$$I = \frac{\text{Pow}}{\text{Amp}^2} \quad P = W/t$$

*Intensity* is DIRECTLY related to *amplitude*

Damping: further you get from the center → quieter it will be

**Inverse Square Law:**  $I_1 r_1^2 = I_2 r_2^2$

**Volume (B) :** subjective (**decibels**)

Relative Intensity Level → loudness level

Volume is DIRECTLY related to *Intensity*

Volume is DIRECTLY related to *Frequency*

*f* standard = 1,000 Hz

**Intensity Range**

Threshold of hearing ( $I_0$ ) =  $1 \times 10^{-12} \text{ w/m}^2$

Threshold of sound =  $1 \text{ w/m}^2$

$$\beta = 10 \log \frac{I}{1 \times 10^{-12} \text{ w/m}^2}$$

"How many powers of 10 are in that number?"

$$\text{Decibel} = \frac{\text{w/m}^2}{\text{w/m}^2}$$

**Pitch and Tone**

$I \rightarrow$  volume  $f \rightarrow$  pitch

Notes and tones: pitch with recognizable frequencies Laws of Pitch:

1.  $f$  is INDIRECTLY related to *length*
2.  $f$  is DIRECTLY related to *tension* (Ft)
3.  $f$  is INDIRECTLY related to *diameter* (d)
4.  $f$  is INDIRECTLY related to *density* (D)

**Beats:** the resultant interference pattern of 2 notes

close in frequency but not exact

Creates nodes (sharps and flats)

**Doppler Effect:** the apparent change in frequency of a sound due to the relative motion of either the observer or the source of both

**Resonate:** when you cause something to vibrate at its natural frequency

Music → repeating wave pattern

Noise → no repeating wave pattern

Consonance → sounds GOOD

Dissonance → sounds BAD

**Decibel:**

I	B
$1 \times 10^{-12}$	<b>0 db</b>
$1 \times 10^{-11}$	<b>10 db</b>
$1 \times 10^{-10}$	20 db
....	.....
$1 \times 10^{-2}$	100 db
$1 \times 10^{-1}$	110 db
1	120 db

**Natural Frequencies**  $l = 170 / \text{Hz}$

Brass/String n	name	synm	wavl ( $\lambda$ )	1	f
$f$	Fund	1 <sup>st</sup> har.	$2l$	$\frac{1}{2} \lambda$	$v/2l$
$f_2$	1 <sup>st</sup> ov.	2 <sup>nd</sup> har.	$l$	$\lambda$	$v/l$
$f_3$	2 <sup>nd</sup> ov.	3 <sup>rd</sup> har.	$2/3l$	$3/2 \lambda$	$3v/2l$
$f_4$	3 <sup>rd</sup> ov.	4 <sup>th</sup> har.	$1/2l$	$2\lambda$	$2v/l$
$f_n = \frac{nv}{2l}$		$hn = \frac{2l}{n}$		$f_n = Nf_1$	

Woodwind n	name	synm	wavl ( $\lambda$ )	1	f
$f$	Fund	1 <sup>st</sup> har.	$4l$	$\frac{1}{4} \lambda$	$v/4l$
$f_2$	....	....	....	....	....
$f_3$	1 <sup>st</sup> ov.	2 <sup>nd</sup> har.	$4/3l$	$3/4 \lambda$	$3v/4l$
$f_4$	....	....	....	....	....
$f_5$	2 <sup>nd</sup> ov.	3 <sup>rd</sup> har.	$4/5l$	$5/4\lambda$	$5v/4l$
$f_n = \frac{nv}{2l}$		$hn = \frac{2l}{n}$			

## Instruments

**String** Produced by: plucking string, bowing  
Change pitch : length, diameter, tension, density

**Brass** Produce by : buzzing mouth piece  
Change pitch : length of pipe (valves), buzzing

**Woodwind** Produced by : reed vibrating  
Change pitch : pads, holes

**Edge tones:** narrow streams of air split by edge

**Helmholtz Resonance:** edge tone with bottle (open hole)

## Light

<u>Particle</u>	<u>Wave</u>
+ Newton said so	+ Thomas Young – 2 slit ex
+ Beams / Wave	+ reflection, refraction,
+ travel in straight lines	diffraction, interference
+Hertz – light is energy	
+ Einstein – wave particle duality	

**Polarized Light:** Light oriented to one plane (calc.)

**Liquid Filter Display :** lets only one degree of light in

**Visible Spectrum:** Radio \* Micro \* Infrared \* Ultraviolet \* Xrays\* Gamma  
Big wavelength →→→→→→→ Small wavelength

Red Orange Yellow Green Blue Indigo Violet

Transparent: see through it and light passes (Windows, glass)

Translucent: can NOT see through it, light passes (frosted glass)

Opaque : can NOT see through it, NO light passes Source: makes and emits light

Luminous: sun

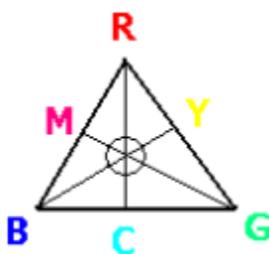
Luminate: moon

Light Year: takes 8.3 min. to get light from sun Dispersion: breaking up light into colors (prism)

## Colors

Cones in eye pick up 3 primary colors of light  
Additive

<u>Primary</u>	<u>Secondary</u>
BLUE	YELLOW
RED	CYAN
GREEN	MAGENTA
* More than one light source	



## Subtractive

<u>Primary</u>	<u>Secondary</u>
YELLOW	BLUE
CYAN	RED
MAGENTA	GREEN
*only one light source	
* darker colors	

## Shades of Colors

Hue: proportion of color

Saturation : amount of white mixed with color

Brightness : amount of black mixed with color

## Reflection

Smooth:  $\theta_i = \theta_r$

Diffuse: "scatters light" obeys laws still

## Refraction

Index of Refraction  $n = \frac{3 \times 10^8}{v}$

(speed in whatever medium)

Air : 1.00 Water : 1.33 Glass : 1.52

## Snell's Law

- \* n is INDIRECTLY related to  $\theta$
  - \* n is INDIRECTLY related to speed
  - \* v is DIRECTLY related to  $\theta$
- $$n_1 \sin \theta_1 = n_2 \sin \theta_2$$

## Lasers

Critical angle( $\theta_c$ ): the  $\theta_1$  that produces the angle that is larger than  $\theta_c$ .  
Total Internal Reflection: no refraction

## Optics

Reflection: mirrors

Refraction: lenses

## Mirrors

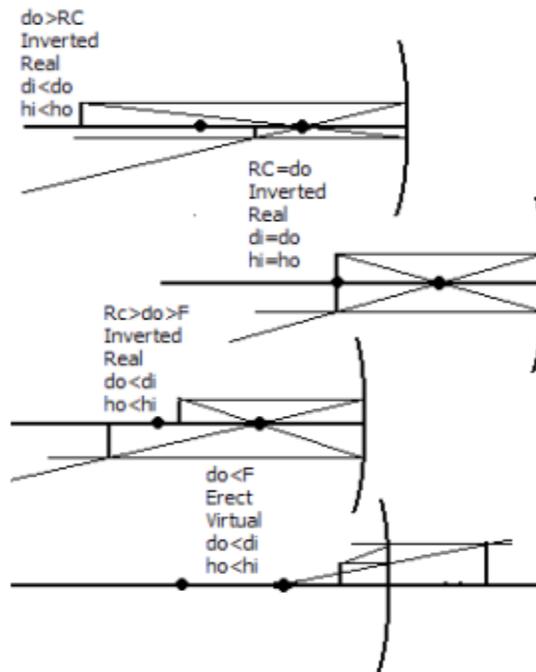
Concave: converging and upside down after foc. Pt

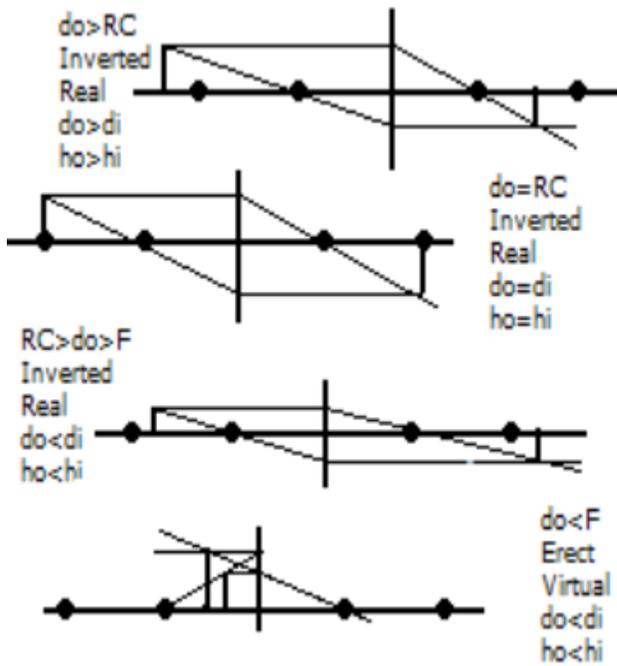
Convex: diverging, upright and smaller

Magnification:  $M = \frac{h_i}{h_o}$        $M > 1 = \text{big}$

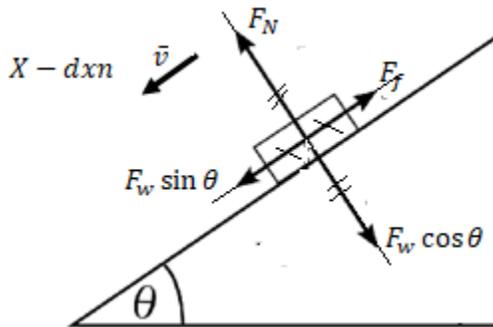
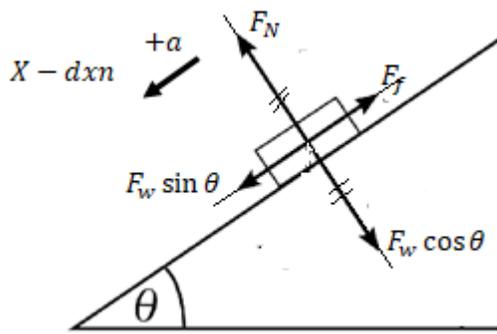
$M < 1 = \text{small}$

$$h_i = \frac{h_o d_i}{d_o} \quad f = \frac{d_o d_i}{d_o + d_i} \quad d_o = \frac{d_i f}{d_i - f} \quad d_i = \frac{d_o f}{d_o - f}$$

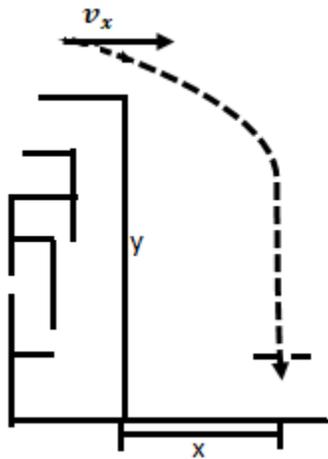




<u>If you have this</u>	<u>Do this</u>	<u>To get this</u>
N	$\times .225$	lb.
lb.	$\div .225$	N
N	$\div 9.8$	Kg
Kg	$\times 9.8$	N
lb.	$\times .454$	Kg
Kg	$\div .454$	lb.



Buddy rides his bike off the top of a 24.5 m high building going 6.25 m/s. What will his range be?  
 Handle projectile motion problems in two columns representing the two directions (independent of each other)



If you're looking for "x", start in the "y" so find "t", (so vice versa)

**X finish here**

$$v_x = 6.25$$

$$\chi = ?$$

$$\chi = v_x t$$

$$= (6.25)(2.236)$$

$$= 13.9754$$

$$\chi = 14.0 \text{ m}$$

**Y start here**

$$Y = 24.5$$

$$g = 9.8$$

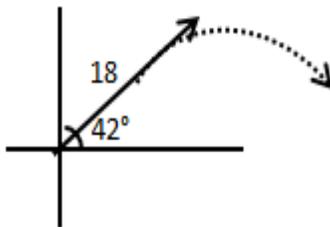
$$t = \sqrt{\frac{2y}{g}}$$

$$= \sqrt{\frac{2(24.5)}{9.8}}$$

$$= 2.236$$

Notice that "t" is the link between the two directions

Ex- A football is kicked at 18 m/s, 42° above the horizontal ground. Find both its maximum height and range?  
set your problem up in two columns again



**X** do the components first

$$v_x = V \cos \theta$$

$$= 18 \cos 42$$

$$= 13.376$$

For range

$$\chi = v_x t$$

$$= (13.4)(2.46)$$

$$= 32.879$$

$$\chi = 33 \text{ m}$$

$Y_{max} = 7.3 \text{ m}$  Make sure you use the correct speeds in the correct places!!!

**Y**

$$v_y = V \sin \theta$$

$$= 18 \sin 42$$

$$= 12.044$$

The Y will always give you "e"

$$t = \frac{2v_0}{g} = \frac{2(12)}{9.8}$$

$$= 2.458$$

$$Y_{max} = \frac{v_0^2}{2g} = \frac{(12)^2}{19.6} \text{ for height}$$

$$= 7.3469$$

5.

$$\mu = 22$$

$$v_0 = 8.96 \frac{1}{3}$$

$$v = \theta$$

$$F_w = 60N$$

$$m = 6.122 \text{ kg}$$

$$F_f = ? N$$

$$a = -$$

$$\chi_0 = 0$$

$$\chi = ? m$$

$$t = ? \Delta\mu$$

$$F_f = \mu F_N = (0.22)(60) = 13.2$$

$$F_f = 13.2N$$

$$a = \frac{F_f}{M} = \frac{13.2}{6.122} = 2.156 \dots$$

$$v^2 = v_0^2 + 2a(\chi - \chi_0)$$

$$\frac{-v_0^2}{2a} \chi = \frac{-(8.96)^2}{2(-2.156)}$$

$$= 18.61815$$

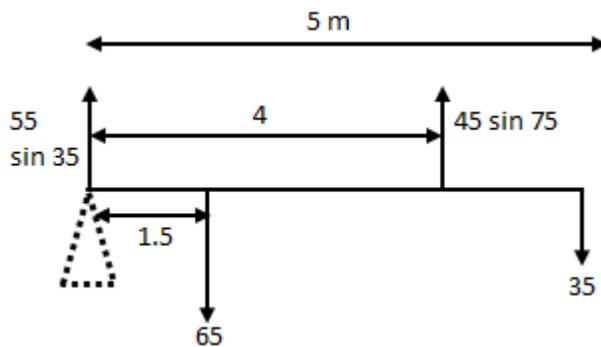
$$\chi = 18.6 m$$

$$v = v_0 + at$$

$$\frac{-v_0}{a} = t = \frac{-8.96}{-2.156}$$

$$T=4.1 \text{ base}$$

$$= 4.1558$$



$$\Sigma F \uparrow = \Sigma F \downarrow$$

$$(55 \sin 35) + (45 \sin 75) = 65 + 35$$

$$75.013 = 100$$

$$\therefore F \text{ is "up" } 25 N$$

$$\Sigma \tau_c = \Sigma \tau_{cc}$$

$$(65)(1.5) + (35)(5) = (45 \sin 75)(4) + (25)(l)$$

$$3.9453 l$$

$$F = 25N, \text{ up, } 39. M \text{ from left end}$$

$$\chi_0 = 0$$

$$\chi = 12$$

$$v_0 = 15$$

$$v = 0$$

$$a = -$$

$$M = 6.73$$

$$F_w = 66 (F_N)$$

$$\mu = ?$$

$$v^2 = v_0^2 + 2a(\chi - \chi_0)$$

$$\frac{-v_0^2}{2\chi} = a = -\frac{15^2}{2(12)} = 9.375$$

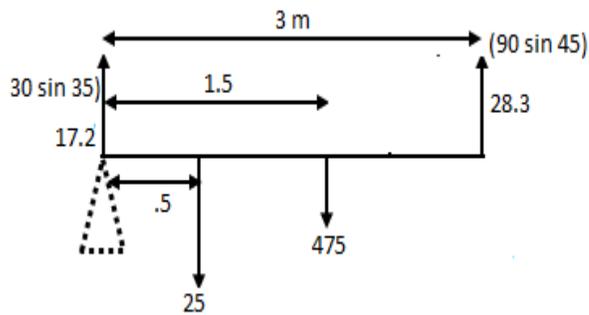
$$F_f = ma = (6.73)(9.375)$$

$$= 63.09$$

$$\mu = \frac{F_f}{F_N} = \frac{63.09}{66} = .95596$$

$$\mu = 0.956$$

4.



$$\Sigma F \uparrow = \Sigma F \downarrow$$

$$(17.2 + 28.3) = (25 + 475)$$

$$45.5 = 500$$

$$F_{up} = 455 \text{ N}$$

$$\Sigma \tau_c = \Sigma \tau_{cc}$$

$$(25)(.5) + (475)(1.5) = (28.3)(3) + (455)(l)$$

$$= 1.4068 = l$$

$$F_{up} = 455 \text{ N}, 1.4 \text{ M from left end}$$

Ex- How much momentum does a 6.0 kg object have if it is moving at 3.0 m/s? What force would it take to bring it to rest in 2.0 seconds?

$$p = ? \text{ Ns}$$

$$m = 6 \text{ kg}$$

$$v = 3 \text{ m/s}$$

$$p_0 = 18$$

$$p = 0$$

$$F = ?$$

$$t = 2$$

$$p = mv = (6)(3) = 18$$

$$p = 18 \text{ Ns}$$

$$= \Delta p = -18$$

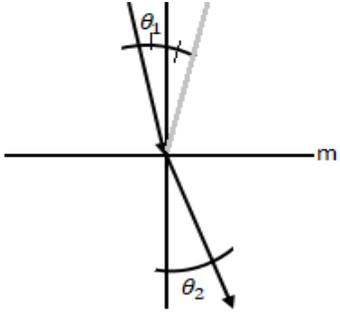
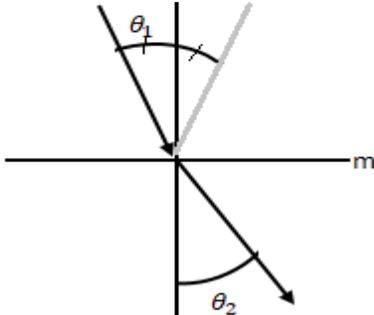
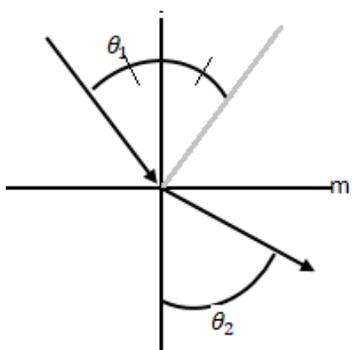
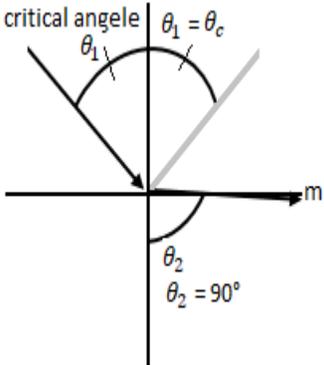
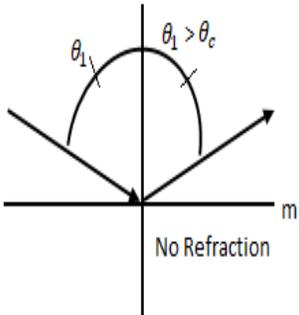
$$\Delta p = F \Delta t$$

$$F = \frac{\Delta p}{\Delta t} = \frac{-18}{2} = -9$$

$$F = 9.0 \text{ N in opposite dxn}$$

### Total Internal Reflection

As you move through each example, notice the angle of incidence gets larger and larger also note that this causes the angle of refraction to increase as well. There will come a point where the angle of incidence causes the angle of refraction to be ninety degrees.... That is the refracted light seems to go spread out along the boundary (situation # 4 below). The angle of incidence that causes this to happen is called 'critical angle' for that medium. If the angle of incidence arrives any larger than the critical angle (situation #5)

<p>1.</p> 	<p>2.</p> 	<p>3.</p>  <p>We say that it is total internally reflex total internal Reflection occurs when angel of incidence arrive larger that critical angle for the median.</p>
<p>4.</p>  <p>critical angele <math>\theta_1 = \theta_c</math>  <math>\theta_2 = 90^\circ</math></p>	<p>5.</p>  <p><math>\theta_1 &gt; \theta_c</math>          No Refraction</p>	<p>TIR          If <math>\theta_1 = \theta_c \dots \dots \theta_2</math>          if <math>\theta_1 &gt; \theta_c \dots \dots TI</math></p>

Ex. An 18 cm flywheel slows from 8.0 rev/sec to 3.0 rev/sec over a 3.5 second time interval. Find its angular deceleration & its angular & linear displacements.

$\omega_0 = 8.0 \frac{\text{rev}}{\text{sec}} = 50.26 \frac{\text{rad}}{\text{sec}}$ Must convert to RAD to do this problem	$\omega = \omega_0 + \alpha t$
$\omega = 3 \text{ rev/sec} = 18.85 \text{ RAD/s}$	$\frac{\omega - \omega_0}{t} = \alpha = \frac{18.8 - 50.2}{3.5}$
$t = 3.5 \text{ sec}$	$= -8.9742$
$\alpha = -? \text{ RAD/s}^2$ simple kinematics	$\theta = \theta_0 + \frac{1}{2}(\omega + \omega_0)t$
$\theta_0 = \theta$	$= (.5)(50.26 + 18.85)(3.5)$
$\theta = ? \text{ RAD}$	$\theta = 120 \text{ RAD} = 120.9425$
$\chi = ? \text{ RAD}$	$\chi = \theta r = [120.94](.18)$
Ang. To LIN. conversion $\chi = ? \text{ M}$ $\chi = 22 \text{ m}$	$= 21.7696.$

6.

(Open)  
 $l = 0.86 \text{ m}$

$$f_1 = \frac{Nv}{2l} = \frac{(1)(344)}{2(.86)} = 200$$

$v = 344 \text{ m/s}$

$$f_1 = 200 \text{ Hz}$$

$f_1 = ? \text{ Hz}$

$$f_1 = \frac{Nv}{4l} = \frac{(1)(344)}{2(.86)} = 100$$

(closed )

$$f_1 = 100 \text{ Hz}$$

$f_1 = ? \text{ Hz}$